Go: syscalls and the scheduler

Rahul Tiwari

Software Engineer at Simpl

Backend Developer.

Can write Go and Python.

Loves football, FOSS, classical music and metacognition in the order mentioned.

Why should you spend the next 15 minutes or so listening to me?

- Understand how high level languages function under the hood
- To become capable in understanding and debugging your program
- And if you're curious in general

What are syscalls?

```
SYSCALLS(2)

NAME top

syscalls - Linux system calls

SYNOPSIS top

Linux system calls.

DESCRIPTION top

The system call is the fundamental interface between an application and the Linux kernel.
```

How do I see syscalls?

strace

```
STRACE(1)

NAME

strace - trace system calls and signals

DESCRIPTION

In the simplest case strace runs the specified command until it exits.

It intercepts and records the system calls which are called by a process and the signals which are received by a process.
```

dtruss (A handy Mac replacement)

```
NAME

    dtruss - process syscall details. Uses DTrace.

DESCRIPTION

    dtruss prints details on process system calls. It is like a DTrace
    version of truss, and has been designed to be less intrusive than truss.
```

Coming back to Go

```
// A simple Hello world Go program
package main

import (
  "fmt"
)

func main() {
  fmt.Println("Hello world!")
}
```



Tracing syscalls

```
# Output of sudo dtruss -f ./main
  PID/THRD SYSCALL(args)
                               = return
Hello world!
16028/0x1d793: fork()
                           = 0 0
16028/0x1d793: access("/AppleInternal/XBS/.isChrooted\0
 ь ", 0x0, 0x0)
                   = -1 Err#2
16028/0x1d793:
 ┗ bsdthread_register(0x193D79084, 0x193D79078, 0x4000) =
 L 1073742303 0
16028/0x1d793:
 bsdthread_create(0x1046644C0, 0x1400003C000, 0x16B883000) =
 L 1804087296 0
16028/0x1d793: __pthread_sigmask(0x3, 0x16B7FB6C8, 0x0) = 0 0
16028/0x1d796: fork()
                           = 0 0
16028/0x1d793:
 ь bsdthread_create(0x1046644C0, 0x1400003C480, 0x16B90F000) =
 L 1804660736 0
16028/0x1d797: fork()
                           = 0 0
16028/0 \times 1d793: sigreturn(0x14000009C18, 0x1E, 0x97346E51C6D2C79B) =
 ⊾ 0 Err#–2
16028/0x1d797:
 bsdthread_create(0x1046644C0, 0x14000080000, 0x16B99B000) =
 L 1805234176 0
16028/0x1d797: __pthread_sigmask(0x3, 0x16B90ECD8, 0x0) = 0 0
16028/0×1d793: madvise(0×1400005C000, 0×8000, 0×8) = 0 0
16028/0x1d798: fork()
                           = 0 0
```

```
16028/0x1d796: __semwait_signal(0x903, 0x0, 0x1) = -1 Err#60
16028/0 \times 1d793: mlock(0x14000060000, 0x4000, 0x0) = 0 0
16028/0 \times 1d798: thread_selfid(0x0, 0x0, 0x0) = 120728 0
16028/0 \times 1d793: __pthread_sigmask(0 x 3, 0 x 10472C1B0, 0 x 16B7FB588) = 0
 ւ 0
16028/0 \times 1d798: sigaltstack(0x0, 0x16B99AE70, 0x0) = 0 0
16028/0 \times 1d797: __semwait_signal(0 \times 903, 0 \times 0, 0 \times 1) = -1 Err#60
16028/0 \times 1d798: sigaltstack(0 × 16B99AE30, 0 × 0, 0 × 0) = 0 0
16028/0 \times 1d798: __pthread_sigmask(0 x 3, 0 x 16B99AE84, 0 x 0) = 0 0
16028/0x1d793:
 L 1805807616 0
16028/0 \times 1d798: psynch_cvsignal(0x1400003C820, 0x100, 0x0) = 257 0
16028/0x1d799: fork()
                             = 0 0
028/0x1d793: write(0x1, "Hello world!\n\0", 0xD)
16028/0 \times 1d796: __semwait_signal(0 \times 903, 0 \times 0, 0 \times 1) = -1 Err#60
16028/0x1d793: kqueue(0x0, 0x0, 0x0)
                                          = 3 0
```

Why more than one thread for just printing "Hello world!"

```
// Allow newproc to start new Ms.
mainStarted = true
if GOARCH != "wasm" { // no threads on wasm yet, so no sysmonsystemstack(func() {
newm(sysmon, nil, -1)
})
// Lock the main goroutine onto this, the main OS thread,
   during initialization. Iost programs won't care, but a few
  do require certain calls to be made by the main thread.
  Those can arrange for main main to run in the main thread
// by calling runtime.LockOSThread during initialization
// to preserve the lock.
lockOSThread()
```

- sysmon starts a new thread to run the system monitor.
- Also, the main thread is blocked by the go runtime and hence the Go scheduler has to start a new thread.
- Other threads are needed for running the GC, timing etc.
- Quoting Go runtime

The GOMAXPROCS variable limits the number of operating system threads that can execute user-level Go code simultaneously. There is no limit to the number of threads that can be blocked in system calls on behalf of Go code; those do not count against the GOMAXPROCS limit.

```
package main
import (
 "fmt"
 "runtime"
 "runtime/pprof"
func main() {
 var threadProfile = pprof.Lookup("
⊾ threadcreate")
 fmt.Printf("Number of logical CPUs %d\n
fmt.Printf("Number of OS threads %d\n
┗ ", threadProfile.Count())
 fmt.Printf("Number of goroutines %d\n
┗ ", runtime.NumGoroutine())
 fmt.Println("Hello world!")
```

```
Number of logical CPUs 8
Number of OS threads 5
Number of goroutines 1
Hello world!
```

Diving into the Go scheduler

The scheduler's job is to distribute ready-to-run goroutines over worker threads.

P	M	G
processor, resource that is required to execute Go code.	worker thread, or machine.	goroutine

LRQ	GRQ
Local Run Queue, each P has its own to manage coroutines	for goroutines that have not been assigned to a P yet

Scheduling paradigms

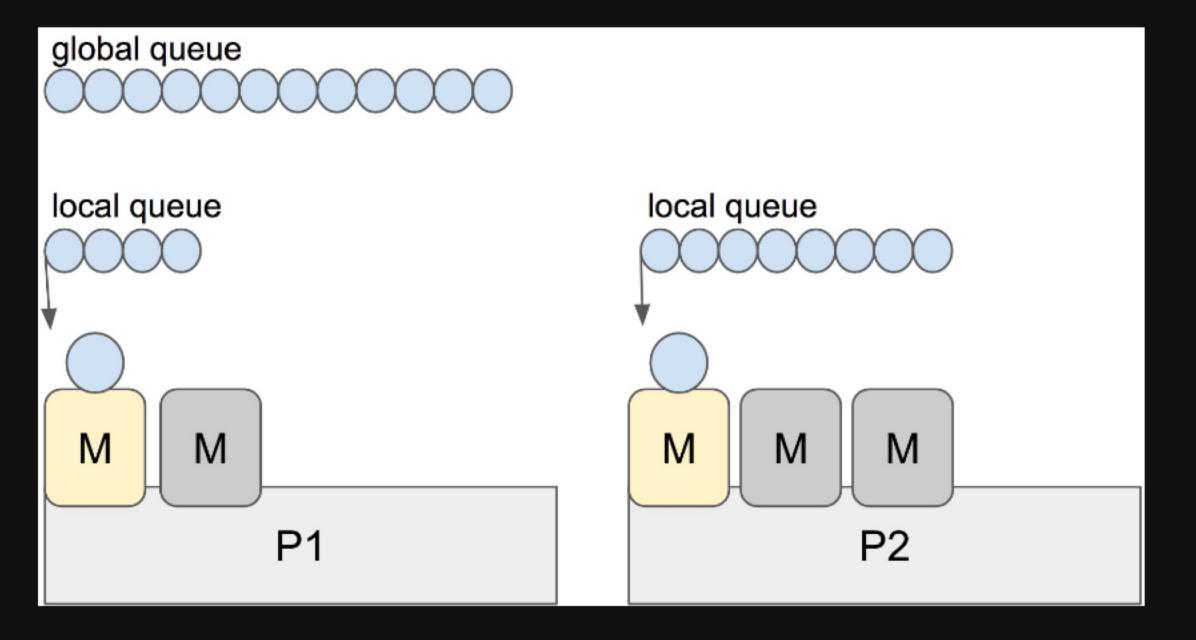
Work stealing

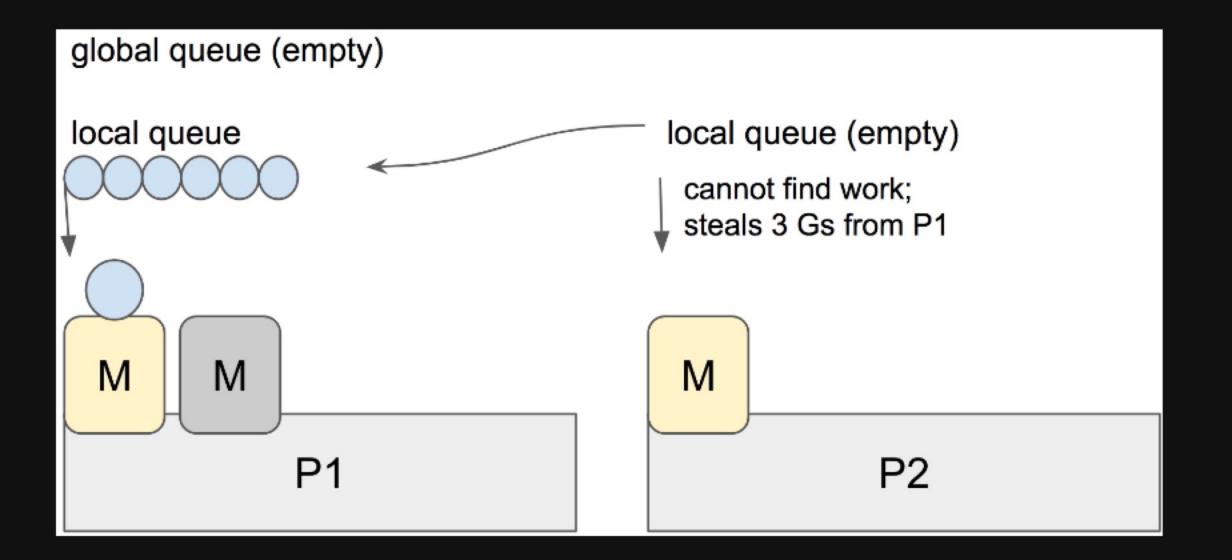
An underutilized processor actively looks for other processor's threads and "steal" some.

Work sharing

When a processor generates new threads, it attempts to migrate some of them to the other processors with the hopes of them being utilized by the idle/underutilized processors.

```
L // One round of scheduler: find a runnable
// goroutine and execute it.
// Never returns.
func schedule() {
```





Does this really happen?

env GODEBUG=scheddetail=1,schedtrace=2 GOMAXPROCS=2 go run main.go

G2: status=4(force gc (idle)) m=-1 lockedm=-1

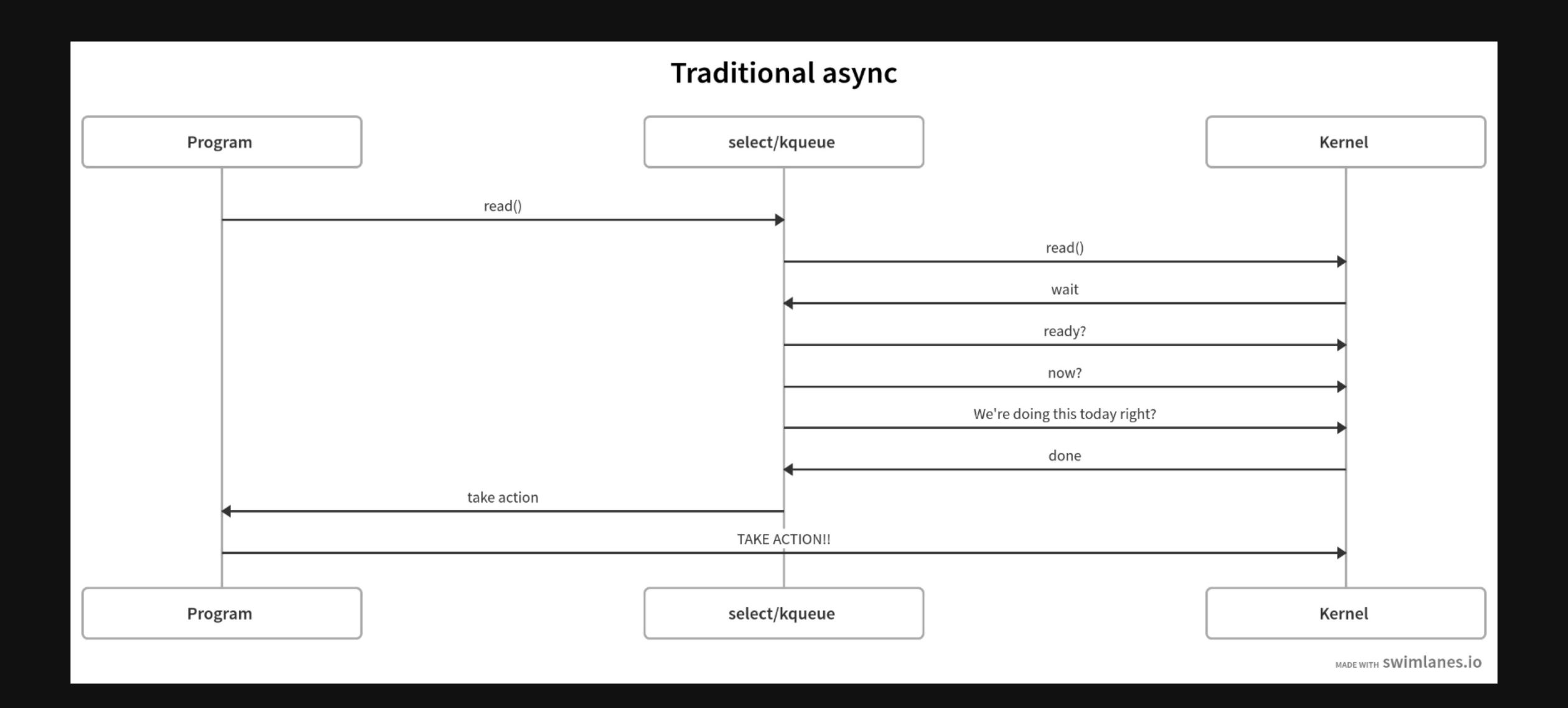
G3: status=4(GC sweep wait) m=-1 lockedm=-1

```
SCHED
   Oms: gomaxprocs=2 idleprocs=0 threads=5 spinningthreads=0 idlethreads=0 runqueue=0 gcwaiting=0 nmidlelocke
  P0: status=1 schedtick=0 syscalltick=0 m=4 runqsize=0 gfreecnt=0 timerslen=0
  P1: status=1 schedtick=2 syscalltick=0 m=3 runqsize=0 gfreecnt=0 timerslen=0
 M4:
   p=0 curg=-1 mallocing=0 throwing=0 preemptoff= locks=1 dying=0 spinning=true blocked=false lockedg=-1
 M3:
 µ p=1 curg=−1 mallocing=0 throwing=0 preemptoff= locks=1 dying=0 spinning=false blocked=false locked=−1
 M2:
   p=-1 curg=-1 mallocing=0 throwing=0 preemptoff= locks=2 dying=0 spinning=false blocked=false lockedg=-1
M1:
   p=-1 curg=17 mallocing=0 throwing=0 preemptoff= locks=0 dying=0 spinning=false blocked=false lockedg=17
 M0:
   p=-1 curg=-1 mallocing=0 throwing=0 preemptoff= locks=1 dying=0 spinning=false blocked=false lockedg=1
  G1: status=1(chan receive) m=-1 lockedm=0
  G17: status=6() m=1 lockedm=1
```

What does the future of syscalls look like?

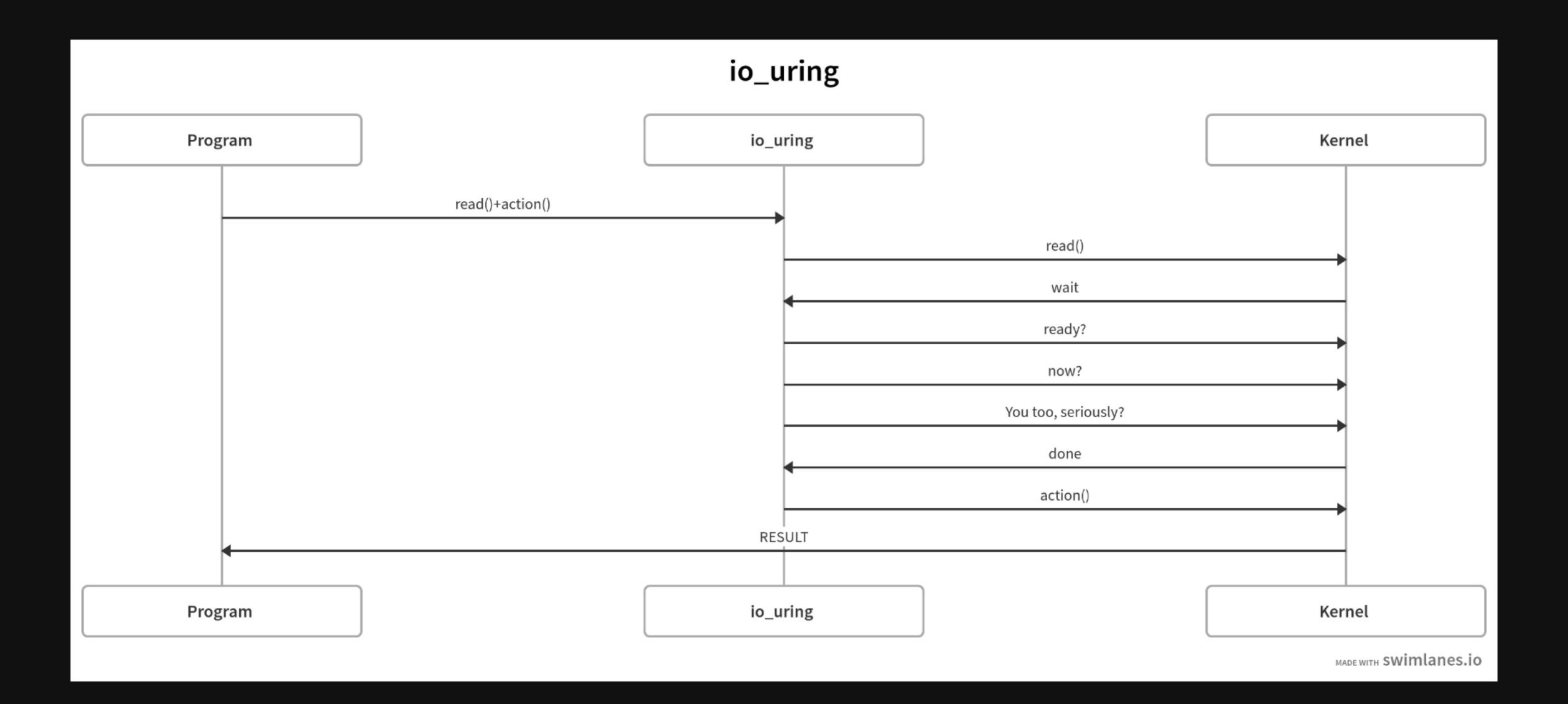
What happens right now?

- All UNIX IO syscalls are synchronous and blocking
- For example, a program calls read(), goes to sleep until the descriptor is ready
- select() and kqueue wake processes so that they can go and perform an action



io_uring

- io_uring subsystem released in mainline kernel in 2019
- Solves for inherently synchronous Unix I/O
- Built around a ring buffer in memory shared between user space and kernel
- Allows submission of operations and collection of results asynchronously.



Questions?

Thank you!